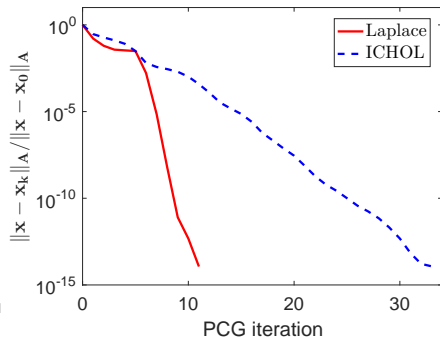
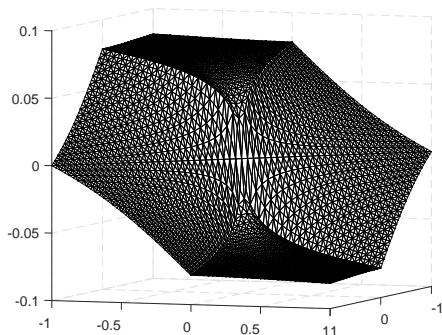


The perfidious condition number

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Manchester, May 2019

The class of elliptic PDEs, an example

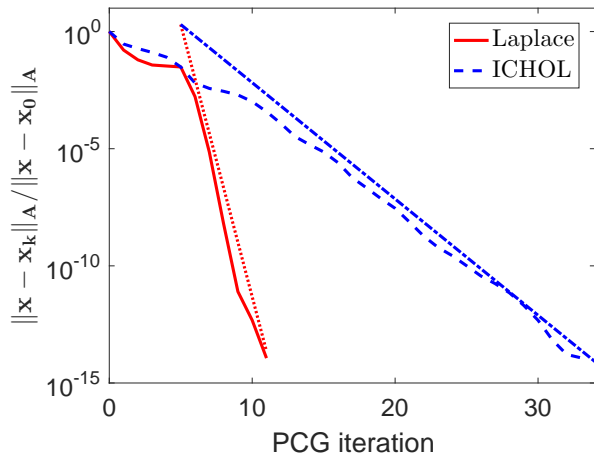


$$-\nabla \cdot (k(x) \nabla u) = 0,$$

Morin, Nochetto, Siebert, SIREV (2002),
linear FE, standard uniform triangulation, $N = 3969$ DOF.

ICHOL PCG (drop-off tolerance $1e-02$), $\kappa \approx 16$;
Laplace operator PCG, $\kappa \approx 160$.

Predicting the computational cost?



Polynomial (Krylov subspace) methods

Consider a linear bounded invertible operator $\mathcal{G} : S \rightarrow S$ and the equation on Hilbert space

$$\mathcal{G}u = f, \quad f \in S.$$

(Infinite dimensional) Krylov subspace methods at step n implicitly construct a finite dimensional approximation \mathcal{G}_n of \mathcal{G} with the desired approximate solution u_n defined by ($u_0 = 0$)

$$u_n := p_{n-1}(\mathcal{G}_n) f \approx u = \mathcal{G}^{-1} f,$$

where $p_{n-1}(\lambda)$ is the associated polynomial of degree at most $n - 1$ and \mathcal{G}_n is obtained by restricting and projecting \mathcal{G} onto the n th Krylov subspace

$$\mathcal{K}_n(\mathcal{G}, f) := \text{span} \{f, \mathcal{G}f, \dots, \mathcal{G}^{n-1}f\}.$$

A.N. Krylov (1931), Gantmakher (1934), Hestenes and Stiefel (1952), Lanczos (1952-53); Karush (1952), Hayes (1954), Stesin (1954), Vorobyev (1958).

- Finite dimensional self-adjoint operators (finite Hermitian matrices)

$$\begin{aligned}
 \mathcal{G} &= \frac{1}{2\pi i} \int_{\Gamma} \lambda (\lambda I_N - \mathcal{G})^{-1} d\lambda = \frac{1}{2\pi i} \sum_{\ell=1}^N \int_{\Gamma_{\ell}} \lambda (\lambda I_N - \mathcal{G})^{-1} d\lambda \\
 &= \sum_{\ell=1}^N Y \operatorname{diag} \left(\frac{1}{2\pi i} \int_{\Gamma_{\ell}} \frac{\lambda}{\lambda - \lambda_{\ell}} d\lambda \right) Y^* = \sum_{\ell=1}^N \lambda_{\ell} y_{\ell} y_{\ell}^* \\
 &= \int \lambda dE(\lambda).
 \end{aligned}$$

- Compact infinite dimensional self-adjoint operators
- Bounded infinite dimensional self-adjoint operators
- Generalization to bounded normal and **non-normal operators**

Using the spectral decomposition $\mathcal{G} = \sum_{\ell=1}^N \lambda_{\ell} y_{\ell} y_{\ell}^*$

Symbolically

$$\begin{aligned} w_1^* \mathcal{G} w_1 &= w_1^* \left(\sum_{\ell=1}^N \lambda_{\ell} y_{\ell} y_{\ell}^* \right) w_1 \equiv w_1^* \left(\int \lambda dE(\lambda) \right) w_1 \\ &= \sum_{\ell=1}^N \lambda_{\ell} |(y_{\ell}, w_1)|^2 = \sum_{\ell=1}^N \lambda_{\ell} \omega_{\ell} = \int \lambda d\omega(\lambda), \end{aligned}$$

where the **spectral function** $E(\lambda)$ of \mathcal{G} is understood to be a nondecreasing family of projections with increasing λ , symbolically $dE(\lambda_{\ell}) \equiv y_{\ell} y_{\ell}^*$ and

$$I = \sum_{\ell=1}^N y_{\ell} y_{\ell}^* \equiv \int dE(\lambda).$$

Hilbert (1906, 1912, 1928), Von Neumann (1927, 1932), Wintner (1929).

CG and Gauss quadrature relationship - the size of errors are equal!

At any iteration step n , CG represents the **matrix formulation of the n -point Gauss quadrature** of the Riemann-Stieltjes integral determined by A and r_0 ,

$$\int_0^\infty \phi(\lambda) d\omega(\lambda) = \sum_{i=1}^n \omega_i^{(n)} \phi(\theta_i^{(n)}) + R_n(\phi).$$

For the function $\phi(\lambda) \equiv \lambda^{-1}$,

$$\frac{\|x - x_0\|_A^2}{\|r_0\|^2} = \text{\textit{n-th Gauss quadrature}} + \frac{\|x - x_n\|_A^2}{\|r_0\|^2}.$$

This has become the basis for CG error estimation; see [Golub, 1994](#); and, e.g., the surveys in [S and Tichý, 2002](#); [Meurant and S, 2006](#); [Golub and Meurant, 2010](#); [Liesen and S, 2013](#).

$$\frac{\|x - x_n\|_A}{\|x - x_0\|_A} \leq 2 \left(\frac{\sqrt{\kappa(A)} - 1}{\sqrt{\kappa(A)} + 1} \right)^n$$

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“... assuming only that the spectrum of the matrix A lies inside the interval $[\lambda_1, \lambda_N]$, we can do no better than Theorem 1.2.2.” [see the bound above]

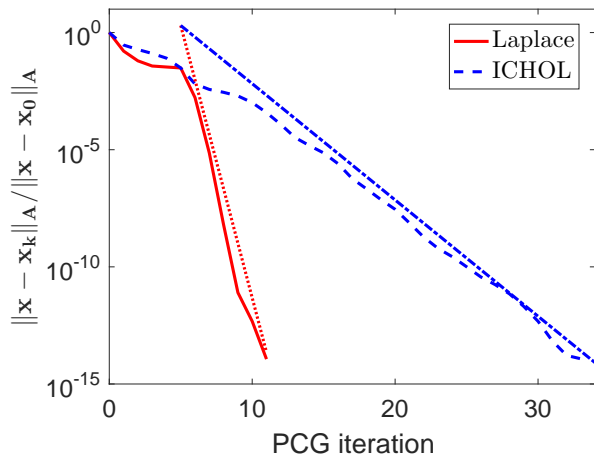
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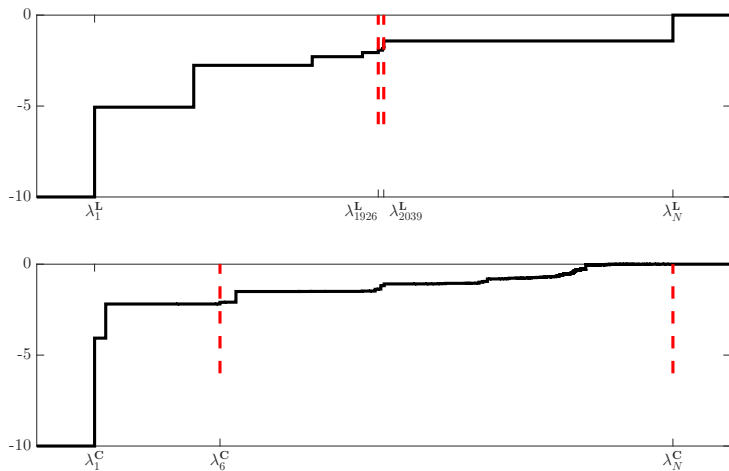
“... assuming only that the spectrum of the matrix A lies inside the interval $[\lambda_1, \lambda_N]$, we can do no better than Theorem 1.2.2.” [see the bound above]

That means that the Chebyshev polynomials-based bound holds for *any* distribution of eigenvalues between λ_1 and λ_N and for *any* distribution of the components of the initial residuals in the individual invariant subspaces.

Back to the elliptic PDE problem example



Various parts of the spectra and convergence behavior



Theorem : (Pairing the eigenvalues and the FE discretization nodal values $k_j, j = 1, \dots, N$)

Let $0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_N$ be the eigenvalues of $\mathbf{L}^{-1}\mathbf{A}$. Let $k(x)$ be bounded and piecewise continuous. Then there exists a (possibly non-unique) permutation π such that the eigenvalues above satisfy

$$\lambda_{\pi(j)} \approx k_j, \quad j = 1, \dots, N.$$

Gergelits, Mardal, Nielsen, S, Laplacian preconditioning of elliptic PDEs: localization of the eigenvalues of the discretized operator, SIAM J. Numer. Anal, 2019.

Here we assume for simplicity a Lagrange FE discretization. The results of the paper are more general.

Clusters of eigenvalues?

- It is not true that CG (or other Krylov subspace methods used for solving systems of linear algebraic equations with symmetric matrices) applied to a matrix with t distinct well separated tight clusters of eigenvalues produces **in general** a large error reduction after t steps; see Sections 5.6.5 and 5.9.1 in [Liesen, S \(2013\)](#). The associated myth has been proved false more than 25 years ago; see [Greenbaum \(1989\)](#); [S \(1991\)](#); [Greenbaum, S \(1992\)](#). Still it is persistently repeated in the literature as an obvious fact.

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- As for systems with nonsymmetric matrices, without specific (strong) assumptions on the structure of invariant subspaces it can not be claimed that distribution of eigenvalues provides insight into the asymptotic behavior of Krylov subspace methods (such as GMRES); see Sections 5.7.4, 5.7.6 and 5.11 of [Liesen, S \(2013\)](#). As above, the relevant results [Greenbaum, S \(1994\)](#); [Greenbaum, Pták, S \(1996\)](#) and [Arioli, Pták, S \(1998\)](#) are more than 20 years old.

- Krylov subspace methods **adapt to the problem**. Exploiting this adaptation is the key to their efficient use.
- Unlike nonlinear problems and/or multilevel methods, the analysis of Krylov subspace methods **can not be based, in general, on contraction arguments**.
- Individual steps **modeling-analysis-discretization-computation** should not be considered separately within isolated disciplines. They form **a single problem**. Operator preconditioning follows this philosophy.
- HPC computations require handling all involved issues.
A posteriori error analysis and stopping criteria are essential ...
- Assumptions must be honored.

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cf. Forsythe, BAMS, 59 (1953):

“There is a great need for clarification of the group of ideas associated with ‘condition.’ With the concept of ‘ill-conditioned’ systems $Ax = b$ goes the idea of preconditioning them. ”

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Málek, S, *Preconditioning and the Conjugate Gradient Method in the Context of Solving PDEs*, SIAM Spotlights, SIAM (2015), Chapter 13:

*“Here we do not argue against using condition numbers ... **where appropriate**. We argue against using them as general unquestioned tools which are considered fully descriptive ... as arguments closing the door for further investigation.”*

“We will go on pondering and meditating, the great mysteries still ahead of us, we will err and stumble on the way, and if we win a little victory, we will be jubilant and thankful, without claiming, however, that we have done something that can eliminate the contribution of all the millenia before us.”

“There remains this: we beech the skilled in these things, that we thought worth showing, they will think openly receiving, and whatever it hides, worth imparting more properly by themselves to the wider mathematical community.”

Thank you very much for your kind patience!

