

The AAA algorithm and its variations to approximate matrix-valued functions

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Outline of the presentation

Introduction

Leja–Bagby algorithm

The Adapted Antoulas-Anderson algorithm and its variations

The AAA algorithm for matrix-valued functions

Introduction

- $\Omega \subset \mathbb{C}$ nonempty, bounded open set.
- $f(z): \Omega \rightarrow \mathbb{C}$ meromorphic function.

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Our goal

Return a rational approximation $r(z)$ of $f(z)$, where

- $r(z) = p(z)/q(z)$ is a (d_1, d_2) rational function, i.e., $p(z)$ and $q(z)$ are coprime polynomials of degree d_1 and d_2 , respectively.
- $\|r(z) - f(z)\| < \epsilon$.

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Three main reasons:

- Compact representation of a function $f(z)$.
- Better convergence than polynomial approximations.
- Extract information about poles or zeros of a function $f(z)$ inside a region $\Omega \subset \mathbb{C}$.

Leja–Bagby algorithm

The Walsh–Hermite integral formula

- $f(z)$ holomorphic in Ω .
- $\Sigma \subset \Omega$ compact and connected set, $\Gamma := \partial\Omega$.
- $(\sigma_j)_{j=0}^m \subset \Sigma$ and $(\xi_j)_{j=1}^m \subset \mathbb{C} \setminus \overline{\Omega}$.

Theorem (Walsh–Hermite integral formula)

Let $s_m = \prod_{j=0}^m (z - \sigma_j) / \prod_{j=1, \xi_j \neq \infty}^m (z - \xi_j)$. Then

$$r_m(z) := \frac{1}{2\pi i} \int_{\Gamma} \left(1 - \frac{s_m(z)}{s(\zeta)} \right) \frac{f(\zeta)}{\zeta - z} d\zeta$$

is the unique (m, m) rational function with preassigned poles ξ_j that interpolates $f(z)$ at the nodes σ_j counting multiplicities.

A basic error estimate gives:

$$\begin{aligned}\|f(z) - r_m(z)\|_2 &= \frac{1}{2\pi i} \left\| \int_{\Gamma} \frac{s_m(z)}{s(\zeta)} \frac{f(\zeta)}{\zeta - z} d\zeta \right\|_2 \\ &\leq K \frac{|s_m(z)|}{\min_{\zeta \in \Gamma} |s_m(\zeta)|},\end{aligned}$$

where K depends on f , Σ and Γ .

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The intuition

We need to minimize $s_m(z)$ on Σ and maximise it on Γ . We call the pair (Σ, Γ) a **condenser**.

The Leja–Bagby algorithm

1. Select a condenser (Σ, Γ) .
2. Start with arbitrary $\sigma_0 \in \Sigma$.
3. For $j = 0, 1, \dots$, recursively set

$$\begin{cases} |s(\sigma_{j+1})| = \max_{z \in \Sigma} |s_j(z)|, \\ |s(\xi_{j+1})| = \min_{z \in \Gamma} |s_j(z)|. \end{cases}$$

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Proposition (Levin, Saff (2006))

Under our assumptions, there exists a positive number $\text{cap}(\Sigma, \Gamma) > 0$, called the *condenser capacity*, such that

$$\limsup_{m \rightarrow \infty} \|f - r_m\|_{\Sigma}^{1/m} \leq e^{-1/\text{cap}(\Sigma, \Gamma)}.$$

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- Exponential decay of the error.
- Immediately generalizable to matrix-valued functions.
- Necessary to preassign the zeros $(\sigma_j)_{j=0}^{d_1}$ and poles $(\xi_j)_{j=0}^{d_2}$.
- The capacity depends on Ω ; it is known only for specific subset (e.g., circles).

The Adapted Antoulas-Anderson algorithm and its variations

The AAA algorithm

- It's a greedy algorithm created by Nakatsukasa, Séte and Trefethen in 2017.

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The AAA algorithm represents $r(z)$ in a barycentric form.

The barycentric representation

We write

$$r_m(z) = \frac{n_m(z)}{d_m(z)} = \frac{\sum_{i=1}^m \frac{w_i f(z_i)}{z - z_i}}{\sum_{i=1}^m \frac{w_i}{z - z_i}},$$

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- z_i are distinct points called **sample/support points**, while w_i are the **weights**.
- $r_m(z_i) = f(z_i)$.
- The functions $r_m(z)$ range all over the set of $(m - 1, m - 1)$ rational functions with no poles at z_i , for $i = 1, \dots, m$.

Input

- A set of M points $Z = \{z_i\}_{i=1}^M$ (mesh grid or contour of Ω).
- The values $f_i := f(z_i)$ for $i = 1, \dots, M$.
- Threshold ϵ , max number of points m_{\max} .

The AAA cycle

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Goal

Denote with $Z^{(m)} = Z \setminus \{z_1, \dots, z_m\}$. Our goal is minimizing

$$\sum_{j=1}^{M-m} \left| f(\tilde{z}_j) d_m(\tilde{z}_j) - n_m(\tilde{z}_j) \right|^2 := \|f_m d_m - n_m\|_{Z^{(m)}}$$

with the constraint $\|w\|_2 = 1$.

The AAA cycle

At the beginning of iteration m :

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2. Remove z_m from $Z^{(m-1)}$ to get $Z^{(m)}$.
3. Write $Z^{(m)} = [Z_1^{(m)}, \dots, Z_{M-m}^{(m)}]^T$. Then

$$\min_{\|w\|_2=1} \|f_m d_m - n_m\|_{Z^{(m)}} = \min_{\|w\|_2=1} \|A^{(m)} w\|,$$

with

$$A^{(m)} = \begin{bmatrix} \frac{f(Z_1^{(m)}) - f(z_1)}{Z_1^{(m)} - z_1} & \cdots & \frac{f(Z_1^{(m)}) - f(z_m)}{Z_1^{(m)} - z_m} \\ \vdots & \ddots & \vdots \\ \frac{F_{M-m}^{(m)} - f(z_1)}{Z_{M-m}^{(m)} - z_1} & \cdots & \frac{F_{M-m}^{(m)} - f(z_m)}{Z_{M-m}^{(m)} - z_m} \end{bmatrix} \in \mathbb{C}^{(M-m) \times m}.$$

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Computational cost

The expensive part of the algorithm are the $(M - j) \times j$ SVD for $j = 1, \dots, m$, therefore the cost is $O(m^3M)$.

The AAA algorithm for matrix-valued functions

What about matrix-valued functions?

From now on, we consider $F(z): \Omega \rightarrow \mathbb{C}^{n \times n}$, $F(z) = \sum_{k=1}^s f_k(z)A_k$.

Remark

- The Leja–Bagby algorithm can be immediately generalized to build $R(z) \approx F(z)$.
- AAA can be called s times. However, it returns s different set of sample points and weights.

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In 2018, Lietaert, Meerbergen et al. proposed the **set-valued AAA** algorithm.

The set-valued AAA algorithm

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$$f_k(z) \approx \frac{\sum_{i=1}^m \frac{w_i f_k(z_i)}{z - z_i}}{\sum_{i=1}^m \frac{w_i}{z - z_i}}, \quad k = 1, \dots, S,$$

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- Greedy strategy: choose $z_m \in Z^{(m-1)}$ such that

$$\max_{i,j} |f_i(z_j) - r_{m-1}(z_j)| = \max_i |f_i(z_m) - r_{m-1}(z_m)|$$

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- Build $R_m(z) = \sum_{k=1}^S r_k(z)A_k$.

The matrix $A^{(m)}$ in the set-valued is given by

$$A^{(m)}W = \begin{bmatrix} \frac{F_{1,1}^{(m)} - f(z_1)}{Z_1^{(m)} - z_1} & \cdots & \frac{F_{1,1}^{(m)} - f(z_m)}{Z_1^{(m)} - z_m} \\ \vdots & \ddots & \vdots \\ \frac{F_{1,M-m}^{(m)} - f(z_1)}{Z_{M-m}^{(m)} - z_1} & \cdots & \frac{F_{1,M-m}^{(m)} - f(z_m)}{Z_{M-m}^{(m)} - z_m} \\ \frac{F_{2,1}^{(m)} - f(z_1)}{Z_1^{(m)} - z_1} & \cdots & \frac{F_{2,1}^{(m)} - f(z_m)}{Z_1^{(m)} - z_m} \\ \vdots & \ddots & \vdots \\ \frac{F_{2,M-m}^{(m)} - f(z_1)}{Z_{M-m}^{(m)} - z_1} & \cdots & \frac{F_{2,M-m}^{(m)} - f(z_m)}{Z_{M-m}^{(m)} - z_m} \\ \vdots & \vdots & \vdots \\ \frac{F_{s,1}^{(m)} - f(z_1)}{Z_1^{(m)} - z_1} & \cdots & \frac{F_{s,1}^{(m)} - f(z_m)}{Z_1^{(m)} - z_m} \\ \vdots & \ddots & \vdots \\ \frac{F_{s,M-m}^{(m)} - f(z_1)}{Z_{M-m}^{(m)} - z_1} & \cdots & \frac{F_{s,M-m}^{(m)} - f(z_m)}{Z_{M-m}^{(m)} - z_m} \end{bmatrix} \begin{bmatrix} W_1 \\ \vdots \\ W_m \end{bmatrix}$$

A simple error bound

Assume $\|f_k(z) - r_k(z)\|_Z < \epsilon$ for every k . Then

$$\begin{aligned}\|F(z) - R(z)\|_Z^2 &\leq \sum_{i=1}^M \left\| \sum_{k=1}^s (f_k(z_i) - r_k(z_i)) A_k \right\|_2^2 \\ &\leq \sum_{k=1}^s \sum_{i=1}^M |f_k(z_i) - r_k(z_i)|^2 \|A_k\|_2^2 \\ &\leq s\epsilon \cdot \max_{1 \leq k \leq s} \|A_k\|_2.\end{aligned}$$

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Issue

The set-valued AAA does not consider $\|A_k\|_2$!

Weighted AAA adaptation

Instead of approximate $f_k(z)$, we can consider $\tilde{f}_k(z) = f_k(z)/\|A_k\|_2$ and $\tilde{A}_k = A_k/\|A_k\|_2$. Under the previous assumptions, we get

$$\begin{aligned}\|F(z) - R(z)\|_Z^2 &\leq \sum_{i=1}^M \left\| \sum_{k=1}^s (\tilde{f}_k(z_i) - \tilde{r}_k(z_i)) \tilde{A}_k \right\|_2^2 \\ &\leq S\epsilon.\end{aligned}$$

Remark

If s is small, then we obtain an error of the same order of magnitude as AAA for scalar functions.

A small example

We want to approximate

$$F(z) = zI + e^{2iz}A_1 + (z + 4)^{1/3}A_2$$

on the unit disk, where $A_i \in \mathbb{C}^{20 \times 20}$ and $\|A_1\|_2 = 1, \|A_2\|_2 = 10^9$.

- We consider the error returned by set-valued AAA and weighted AAA for the scalar functions e^{2iz} and $(z + 4)^{1/3}$
- We consider the approximation error on 300 random points inside the unit circle.

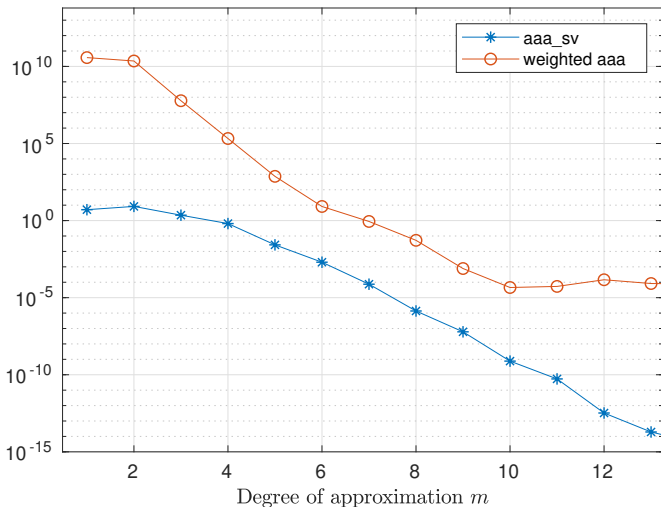


Figure 1: Errors $\max_j \|f_j(z) - r_j(z)\|_Z$ returned by the two implementations of the AAA algorithm for different degrees of approximation.

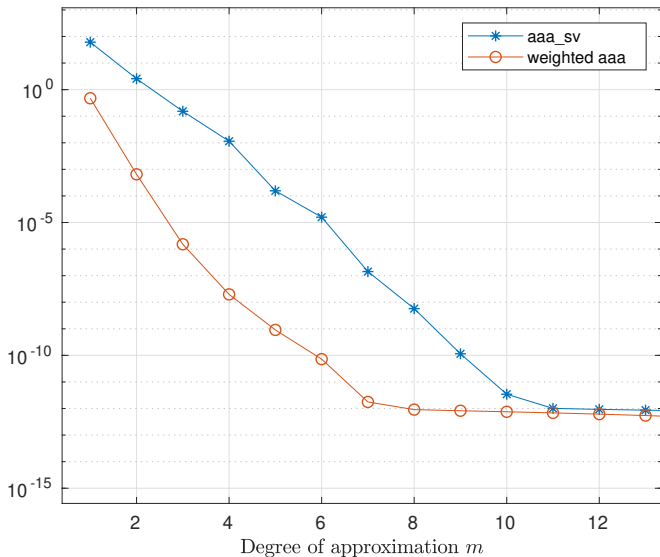


Figure 2: Plot for $\sum_{i=1}^{300} \|F(\tilde{z}_i) - R(\tilde{z}_i)\|_{\infty} / 300$.

The bent_beam problem

The bent_beam problem

We want to approximate the `bent_beam` problem from the NLEVP library:

$$F(\lambda) = \begin{bmatrix} f_-(\lambda) & g_-(\lambda) & -f_+(\lambda) & -g_+(\lambda) & 0 & 0 \\ 0 & 0 & \alpha(\lambda)g_-(\lambda) & \alpha(\lambda)f_+(\lambda) & \sin \beta(\lambda)\ell & 0 \\ g_-(\lambda) & f_+(\lambda) & g_+(\lambda) & f_-(\lambda) & 0 & 0 \\ 0 & 0 & \alpha(\lambda)^2 E l f_-(\lambda) & \alpha(\lambda)^2 E l g_-(\lambda) & -\beta(\lambda)\tau \cos \beta(\lambda)\ell & 0 \\ \alpha(\lambda)^2 E l f_+(\lambda) & \alpha(\lambda)^2 E l g_+(\lambda) & 0 & 0 & 0 & \beta(\lambda)\tau \sin \beta(\lambda)\ell \\ \alpha(\lambda)g_+(\lambda) & \alpha(\lambda)f_-(\lambda) & 0 & 0 & 0 & -\cos \beta(\lambda)\ell \end{bmatrix},$$

where

- $f_+(\lambda) = \cosh \alpha(\lambda)\ell + \cos \alpha(\lambda)\ell$ $f_-(\lambda) = \cosh \alpha(\lambda)\ell - \cos \alpha(\lambda)\ell$;
- $g_+(\lambda) = \sinh \alpha(\lambda)\ell + \sin \alpha(\lambda)\ell$, $g_-(\lambda) = \sinh \alpha(\lambda)\ell - \sin \alpha(\lambda)\ell$;
- $\alpha(\lambda) = \sqrt{\lambda}(m/EI)^{1/4}$, $\beta(\lambda) = \lambda\sqrt{m/\tau}$;
- EI , ℓ , τ and m are physical constants.

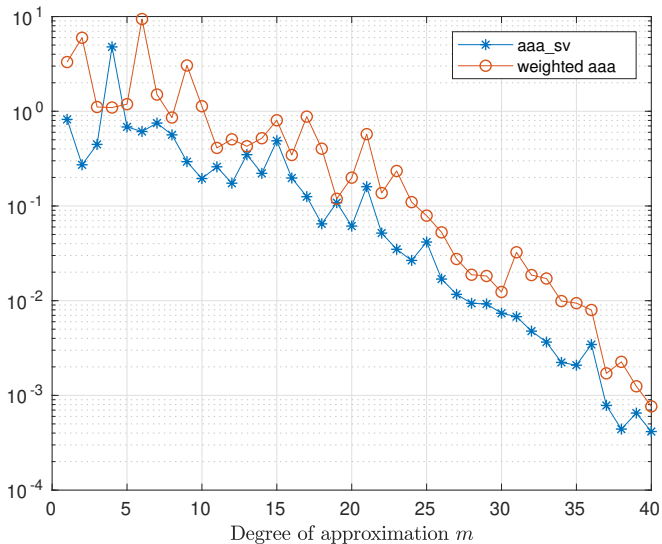


Figure 3: Errors $\max_j \|f_j(z) - r_j(z)\|_z$ returned by the two implementation of the AAA algorithm for different degrees of approximation.

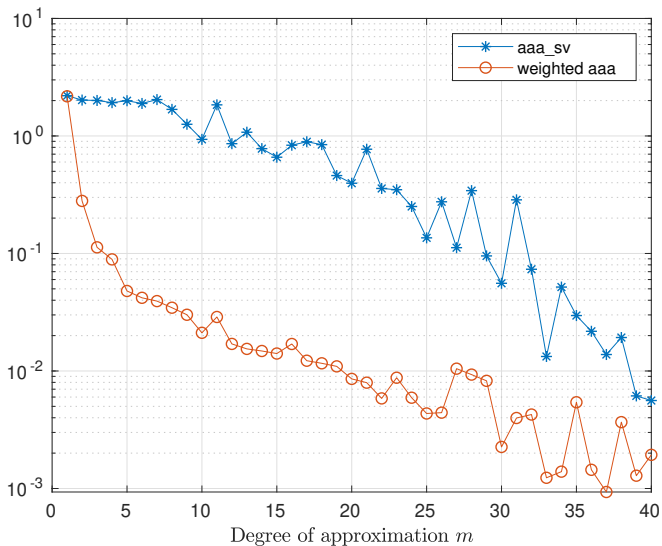


Figure 4: Plot for $\sum_{i=1}^{300} \|F(\tilde{z}_i) - R(\tilde{z}_i)\|_{\infty} / 300$.

$F(z)$ as a black-box function

What if we do not have $f_R(z)$, but only $F(z)$?

AAA for black-box matrix-valued functions

Güttel and Elsworth [2018] suggested the following strategy:

1. Build $f(z) := v_1^* F(z) v_2$, with v_i Gaussian vectors.
2. Approximate $f(z)$ with AAA algorithm and extract w_j, z_j and $f(z_j)$.
3. Use w_j, z_j and $f(z_j)$ to build an approximation $R(z) \approx F(z)$.

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Issue

No robust result about the decay of the approximation error.

A summary

- AAA: Doesn't need preassigned poles, but no result on the decay
- Leja–Bagby: Exponential decay, but needs a condenser.

A Hybrid strategy: AAA + Leja–Bagby

A summary

- AAA: Doesn't need preassigned poles, but no result on the decay
- Leja–Bagby: Exponential decay, but needs a condenser.

The best of two worlds

1. Approximate $f(z) = v_1^* F(z) v_2$ with the AAA algorithm.
2. Extract the zeros σ_j and the poles ξ_j from $r(z) \approx f(z)$.
3. Use the zeros and poles as the condenser $\text{cap}(\Sigma, \Gamma)$ for the Leja–Bagby algorithm on $F(z)$.

The Hadelr problem

We approximate the `hadelr` problem

$$F(z) = (e^z - 1)B + z^2A_2 - 100I,$$

from the NLEVP library, where $B, A_2 \in \mathbb{R}^{600 \times 600}$.

- We assume we only have its black-box form, so we consider $f(z) = v_1^T F(z) v_2$.
- We compare the errors of AAA and of AAA plus Leja–Bagby.

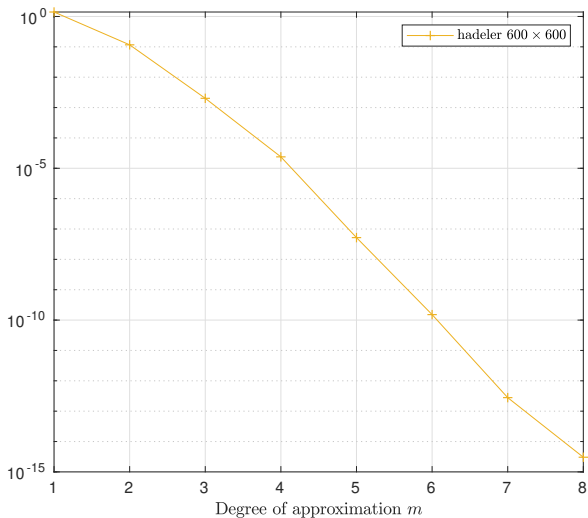


Figure 5: The approximation of $f(z) = v_1^T F(z) v_2$ returned by AAA is very good.

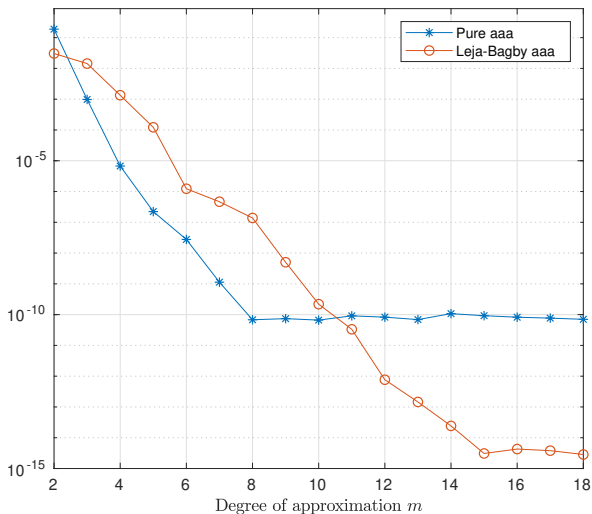


Figure 6: Plot for $\sum_{i=1}^{300} \|F(\tilde{z}_i) - R(\tilde{z}_i)\|_{\infty} / 300$.

The gun problem

We consider the **gun** problem

$$F(z) = K - zM + i(z - \sigma_1^2)^{\frac{1}{2}}W_1i(z - \sigma_2^2)^{\frac{1}{2}}W_2,$$

where the matrices M, K, W_1, W_2 are real and symmetric of size 9956×9956 and $\sigma_1 = 0, \sigma_2 = 108.8774$. We approximate it inside the disk centered in 62500 with radius 50000.

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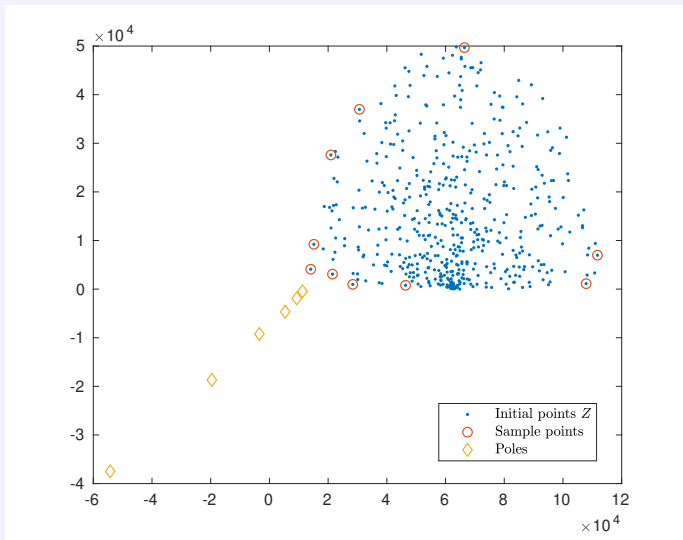


Figure 7: The points used in the AAA algorithm and in Leja–Bagby refinement.

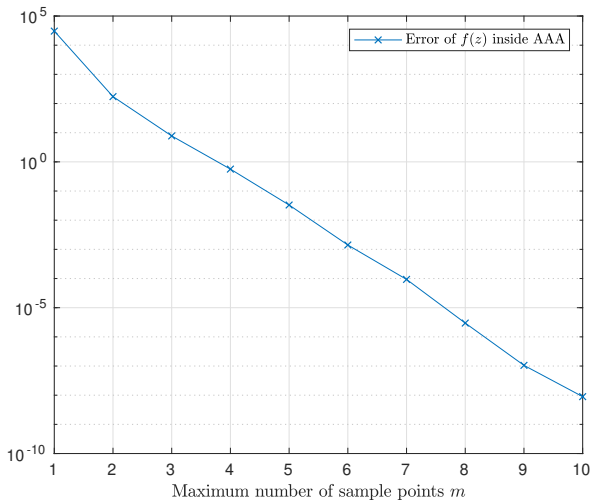


Figure 8: The approximation of $f(z) = v_1^T F(z) v_2$ returned by AAA is good.

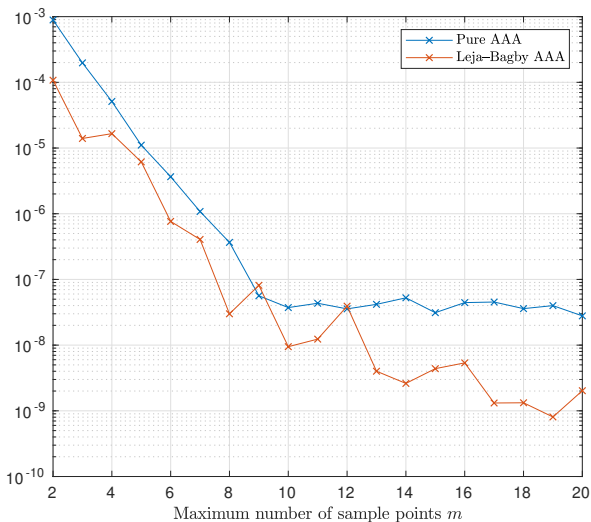


Figure 9: Plot for $\sum_{i=1}^{300} \|F(\tilde{z}_i) - R(\tilde{z}_i)\|_{\infty} / 300$.

Thanks for your attention.
Questions?

Retrieve zeros and poles from barycentric form

In order to find the zeros of a rational function in barycentric form, we need to solve the linear eigenvalue problem

$$\begin{bmatrix} 0 & w_1 & w_2 & \dots & w_m \\ 1 & z_1 & & & \\ & 1 & z_2 & & \\ & & & \ddots & \\ & & & & z_m \\ & & & & & 1 \end{bmatrix} = \lambda \begin{bmatrix} 0 & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & \ddots & \\ & & & & 1 \\ & & & & & 1 \end{bmatrix}.$$

If we want the poles, substitute w_j with $f(z_j)w_j$.

The AAA Cycle

Algorithm 1: Pseudocode for the AAA algorithm

Input: f, Z, m_{\max}, ϵ

Output: $r(z)$.

$Z^{(0)} \leftarrow Z$

$m \leftarrow 0$

while $\|f(z) - r_m(z)\|_{Z^{(m)}} > \epsilon$ *and* $m < m_{\max}$ **do**

 Compute $z_m = \arg \max |fd_{m-1} - n_{m-1}|_{Z^{(m-1)}}$

 Remove z_m from $Z^{(m-1)}$ and get $Z^{(m)}$

 Compute the SVD of matrix $A^{(m)}$

 Retrieve the vector of weights w

 Build $r_m(z)$

$m \leftarrow m + 1$
